



FLUOR

Status and future plans

Vincent Coudé du Foresto



The CHARA-FLUOR niche



- The CHARA/FLUOR combination is unique in the world *and will stay so for the next 10 years* :
 - For the precision on visibility measurements (<1%)
 - => observations with high dynamic range
 - For its usable baselines (330m vs. 200m maxi on VLTI with ATs)
 - => sub-mas resolution in K band
 - For its location in the Northern hemisphere
 - => complementarity with Paranal



Why an rejuvenation (jouvence)?

- Some FLUOR elements (most notably its control system) date back to 1996:
 - => Minimal integration into the CHARA environnement FLUOR (was set up as such in 2002 to accelerate scientific return)
 - => Maintenance increases in complexity and reduces productivity
 - => Little flexibility to follow CHARA's evolutions
- New CHARA functionalities accessible to FLUOR only after better integration:
 - => Simultaneous observations with two instruments (e.g., FLUOR & Vega)
 - => OPD stabilization
 - => Later: AO?
- Some FLUOR functionalities have been demonstrated on a prototype basis but need overhaul in order to be routinely available:
 - => Remote observing (from Meudon)
 - => Spectral dispersion
 - => *Later: multiple beams?*
- Future key science programs (debris disks survey, YSOs, MOLspheres) need those functionalities (and better throughput)

JOUFLU main action items

- **CONTROL**: overhaul control system
 - Client/server architecture under LINUX
 - Total interoperability with CHARA
- **OPD**: remote control of internal OPD and increase of OPD modulation range
 - Adjust internal OPD to another instrument
 - Enable scans longer than the coherence of a single spectral canal in dispersed mode
 - Enable double Fourier interferometry
- **ALIU**: remote control of routine instrument alignments
 - FLUOR set up & troubleshooting with fewer laboratory interventions – and possibility of remote diagnosis
- **OUT**: overhaul detection scheme
 - Dedicated PICNIC-based camera
 - Data throughput improved (serial -> DIO), easier maintenance
 - Current CHARA camera can be reused for fringe tracking and/or IR tip-tilt?



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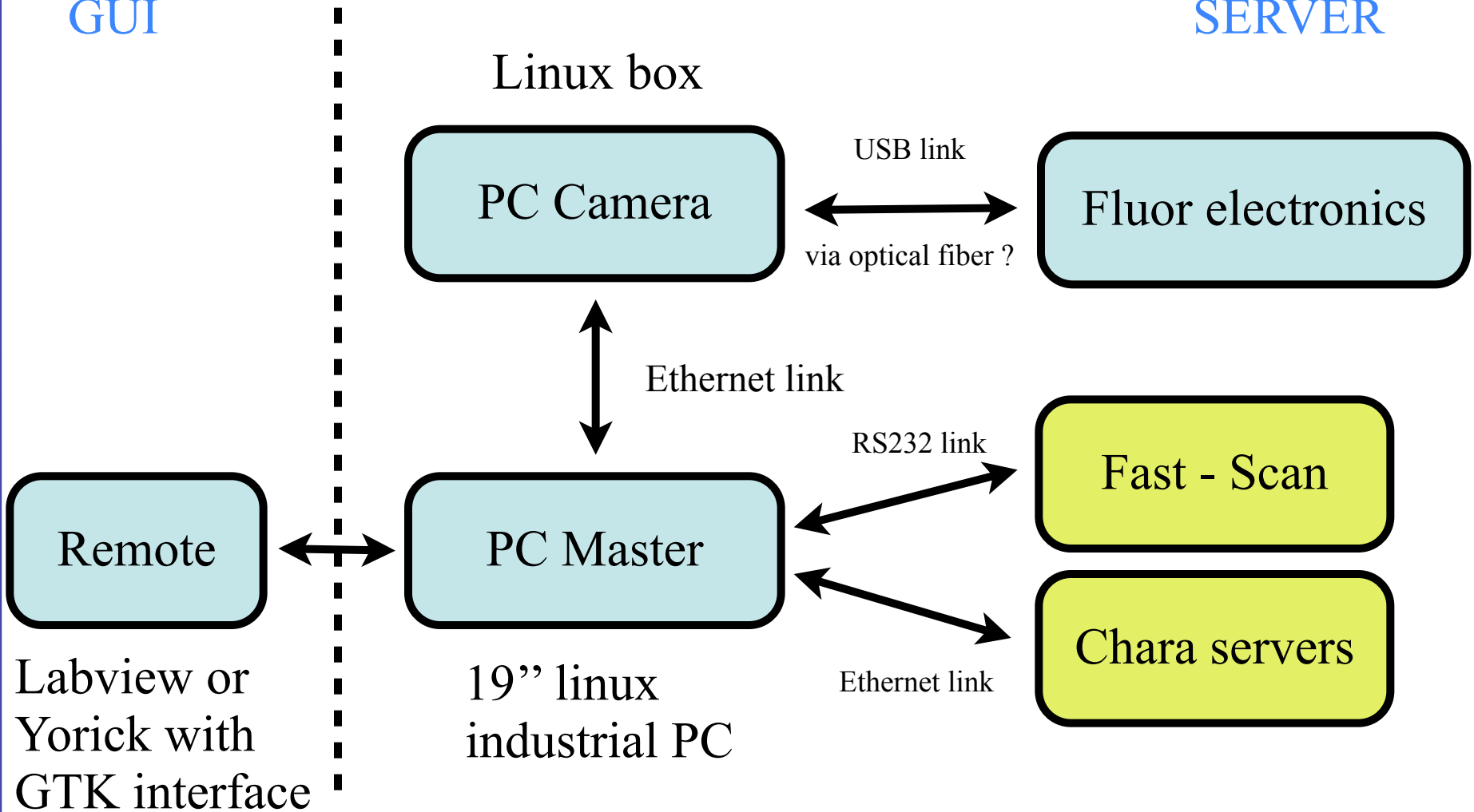
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CONTROL

GUI

SERVER



LESIA





Linux box

- It's an Advantech ARK 5280
- Fanless computer
- Celeron 1.3GHz
- 512MB DDR
- Works on SUSE 9.3 (due to National Instruments drivers) but it can work under Fedora without NI card support





SW on Linux Box

- The linux box is a slave component.
- It receives frames from the electronics (inside frames it knows if it has to store or not)
- It receives orders from the «PC Master»
- The code is written in C++
- Acquisition frames can be store on the PC Camera or on an FTP server



PC Master

- 4U Rackmount Chassis
- Core2 duo 2.2GHz
- 2GB DDR2
- Works also on SUSE 9.3

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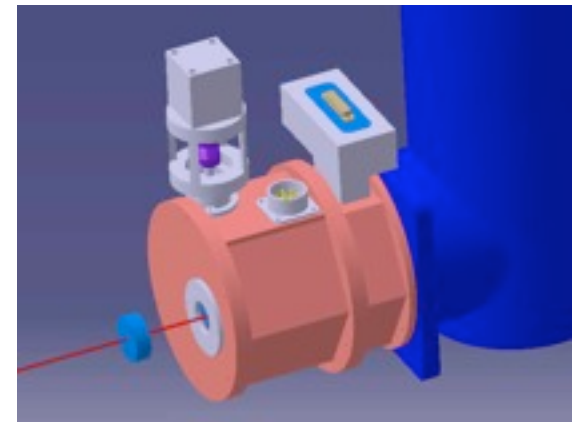
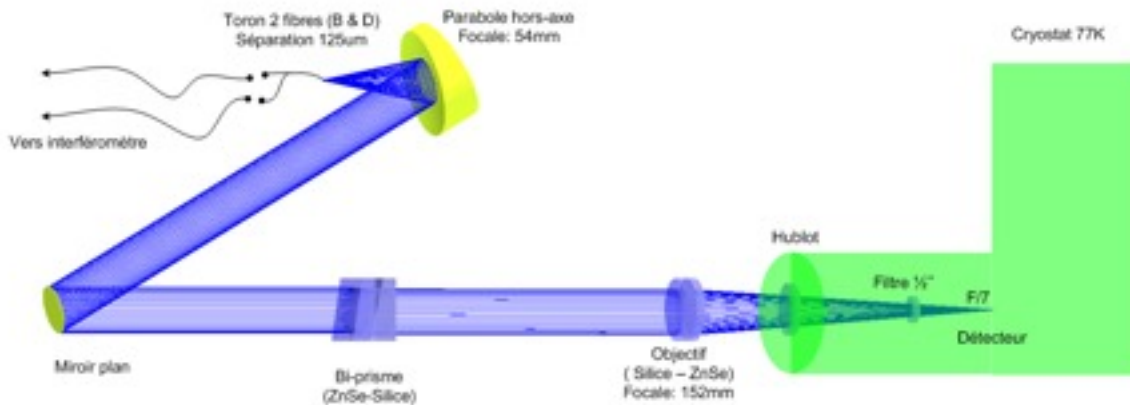
SW on PC Master

- PC Master is without GUI.
- The remote SW controls it over TCP protocol.
- It's the coordinator of the FLUOR bench :
 - get star information
 - modify delay line position
 - send orders to the PC Camera
 - store FITS data in a correct directories structure.



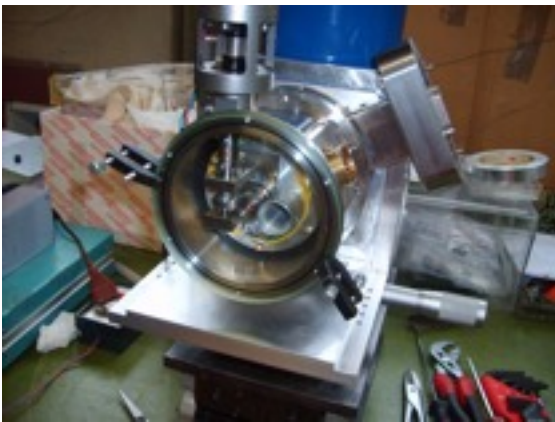
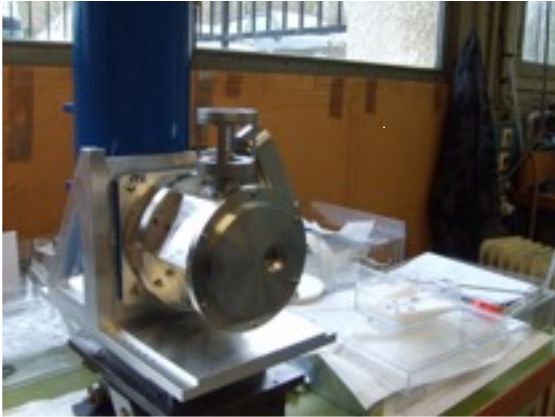
OUT

- Two clone IR cameras being built at LESIA around a PICNIC FPA:
 - CAPER (CAmera PERsée): engineering grade array, for the laboratory
 - CALI (CAmera du Lesia pour l'Interférométrie): science grade array, to be shared between FLUOR and Ohana





Current status



- CAPER cryostat under testing - prior treatment of the parts and integration
 - Analog electronics tested OK - duplication next month
 - Digital electronics - first version delivered this month
 - Base control software tested OK
- => CAPER ready for tests around May
- => Duplication for CALI delivery in Autumn